

## 16-Bit, Ultra Precise, Fast Settling V<sub>OUT</sub> DAC

## FEATURES

- 2µs Settling to 0.0015% for 10V Step
- 1LSB Max DNL and INL Over Industrial Temperature Range
- On-Chip 4-Quadrant Resistors Allow Precise OV to 10V, 0V to -10V or ±10V Outputs
- Low Glitch Impulse: 2nV•s
- Low Noise: 13nV/√Hz
- 36-Lead SSOP Package
- Power-On Reset
- Asynchronous Clear Pin LTC1821: Reset to Zero Scale LTC1821-1: Reset to Midscale

## **APPLICATIONS**

- Process Control and Industrial Automation
- Precision Instrumentation
- Direct Digital Waveform Generation
- Software-Controlled Gain Adjustment
- Automatic Test Equipment

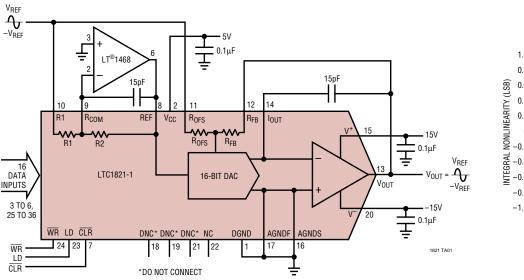
# DESCRIPTION

The LTC<sup>®</sup>1821 is a parallel input 16-bit multiplying voltage output DAC that operates from analog supply voltages of  $\pm$ 5V up to  $\pm$ 15V. INL and DNL are accurate to 1LSB over the industrial temperature range in both unipolar 0V to 10V and bipolar  $\pm$ 10V modes. Precise 16-bit bipolar  $\pm$ 10V outputs are achieved with on-chip 4-quadrant multiplication resistors. The LTC1821 is available in a 36-lead SSOP package and is specified over the industrial temperature range.

The device includes an internal deglitcher circuit that reduces the glitch impulse to less than 2nV•s (typ). The LTC1821 settles to 1LBS in  $2\mu$ s with a full-scale 10V step. The combination of fast, precise settling and ultra low glitch make the LTC1821 ideal for precision industrial control applications.

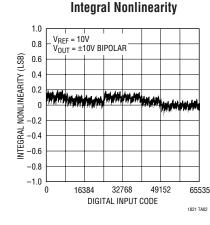
The asynchronous  $\overline{\text{CLR}}$  pin resets the LTC1821 to zero scale and resets the LTC1821-1 to midscale.

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16-Bit, 4-Quadrant Multiplying DAC with a Minimum of External Components

# TYPICAL APPLICATION



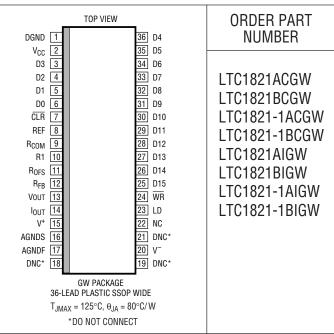
LTC1821/LTC1821-1



#### **ABSOLUTE MAXIMUM RATINGS**

#### (Note 1)

$V_{CC}$ to AGNDF, AGNDS $-0.3V$ to $7V$
$V_{CC}$ to DGND
Total Supply Voltage (V <sup>+</sup> to V <sup>-</sup> )
AGNDF, AGNDS to DGND $V_{CC}$ + 0.3V
DGND to AGNDF, AGNDS V <sub>CC</sub> + 0.3V
REF, R <sub>COM</sub> to AGNDF, AGNDS, DGND ±15V
R <sub>OFS</sub> , R <sub>FB</sub> , R1, to AGNDF, AGNDS, DGND ±15V
Digital Inputs to DGND $-0.3V$ to (V <sub>CC</sub> + 0.3V)
$I_{OUT}$ to AGNDF, AGNDS0.3V to ( $V_{CC}$ + 0.3V)
Maximum Junction Temperature 150°C
Operating Temperature Range
LTC1821C/LTC1821-1C 0°C to 70°C
LTC1821I/LTC1821-1I40°C to 85°C
Storage Temperature Range –65°C to 150°C
Lead Temperature (Soldering, 10 sec) 300°C



#### Consult factory for parts specified with wider operating temperature ranges.

#### **ELECTRICAL CHARACTERISTICS**

The  $\bullet$  denotes specifications which apply over the full operating temperature range, otherwise specifications are T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, V<sup>+</sup> = 15V, V<sup>-</sup> = -15V, V<sub>CC</sub> = 5V, V<sub>REF</sub> = 10V, AGNDF = AGNDS = DGND = 0V.

			LTC1821B/-1B			LTC1821A/-1A				
SYMBOL	PARAMETER	CONDITIONS		MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
Accuracy										
	Resolution		•	16			16			Bits
	Monotonicity		•	16			16			Bits
INL	Integral Nonlinearity	$T_A = 25^{\circ}C$ (Note 2) $T_{MIN}$ to $T_{MAX}$	•			±2 ±2		±0.25 ±0.35	±1 ±1	LSB LSB
DNL	Differential Nonlinearity	T <sub>A</sub> = 25°C T <sub>MIN</sub> to T <sub>MAX</sub>	•			±1 ±1		±0.2 ±0.2	±1 ±1	LSB LSB
GE	Gain Error	Unipolar Mode T <sub>A</sub> = 25°C (Note 3) T <sub>MIN</sub> to T <sub>MAX</sub>	•			±16 ±24		±5 ±8	±16 ±16	LSB LSB
		Bipolar Mode T <sub>A</sub> = 25°C (Note 3) T <sub>MIN</sub> to T <sub>MAX</sub>	•			±16 ±24		±2 ±5	±16 ±16	LSB LSB
	Gain Temperature Coefficient	$\Delta$ Gain/ $\Delta$ Temperature (Note 4)	•		1	3		1	3	ppm/°C
	Unipolar Zero-Scale Error	T <sub>A</sub> = 25°C T <sub>MIN</sub> to T <sub>MAX</sub>	•			±3 ±6		±0.25 ±0.50	±2 ±4	LSB LSB
	Bipolar Zero Error	$T_A = 25^{\circ}C$ $T_{MIN}$ to $T_{MAX}$	•			±12 ±16		±2 ±3	±8 ±10	LSB LSB
PSRR	Power Supply Rejection Ratio	$V_{CC} = 5V \pm 10\%$ V <sup>+</sup> , V <sup>-</sup> = ±4.5V to ±16.5V	•			2 ±2		0.7 ±0.1	2 ±2	LSB/V LSB/V





## **ELECTRICAL CHARACTERISTICS**

The  $\bullet$  denotes specifications which apply over the full operating temperature range, otherwise specifications are T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, V<sup>+</sup> = 15V, V<sup>-</sup> = -15V, V<sub>CC</sub> = 5V, V<sub>REF</sub> = 10V, AGNDF = AGNDS = DGND = 0V.

SYMBOL	PARAMETER	CONDITIONS				MAX	UNITS
Reference	Input						
R <sub>REF</sub>	DAC Input Resistance (Unipolar)	(Note 6)		4.5	6	10	kΩ
R1/R2	R1/R2 Resistance (Bipolar)	(Notes 6, 11)		9	12	20	kΩ
R <sub>OFS</sub> , R <sub>FB</sub>	Feedback and Offset Resistances	(Note 6)		9	12	20	kΩ
AC Perform	nance (Note 4)						
	Output Voltage Settling Time	$\Delta V_{OUT} = 10V \text{ (Notes 7, 8)}$			2		μs
	Midscale Glitch Impulse	(Note 10)			2		nV∙s
	Digital-Feedthrough	(Note 9)			2		nV∙s
	Multiplying Feedthrough Error	$V_{REF} = \pm 10V$ , 10kHz Sine Wave (Note 7)			1		mV <sub>P-P</sub>
	Multiplying Bandwidth	Code = Full Scale (Note 7)			600		kHz
	Output Noise Voltage Density	1kHz to 100kHz (Note 7) Code = Zero Scale Code = Full Scale			13 20		nV/√Hz nV/√Hz
	Output Noise Voltage	0.1Hz to 10Hz (Note 7) Code = Zero Scale Code = Full Scale			0.45 1		μV <sub>RMS</sub> μV <sub>RMS</sub>
	1/f Noise Corner	(Note 7)			30		Hz
Analog Out	tputs (Note 4)		• • •				
V <sub>OUT</sub>	DAC Output Swing	$ \begin{array}{l} R_L = 2k,  V^+ = 15V,  V^- = -15V \\ R_L = 2k,  V^+ = 5V,  V^- = -5V \end{array} $	•	±12.6 ±2.6			V V
	DAC Output Load Regulation	$V^+ = 15V, V^- = -15V, \pm 5mA \text{ Load}$			0.02	0.2	LSB/mA
I <sub>SC</sub>	Short-Circuit Current	$V_{OUT} = 0V, V^+ = 15V, V^- = -15V$		12	40		mA
SR	Slew Rate	$ \begin{array}{l} R_L = 2k, \ V^+ = 15V, \ V^- = -15V \\ R_L = 2k, \ V^+ = 5V, \ V^- = -5V \end{array} $			20 14		V/µs V/µs
Digital Inp	uts						
VIH	Digital Input High Voltage		•	2.4			V
VIL	Digital Input Low Voltage		•			0.8	V
I <sub>IN</sub>	Digital Input Current		•		0.001	±1	μA
CIN	Digital Input Capacitance	(Note 4 ) V <sub>IN</sub> = 0V				8	pF
Timing Cha	aracteristics						
t <sub>DS</sub>	Data to WR Setup Time		•	60	20		ns
t <sub>DH</sub>	Data to WR Hold Time		•	0	-12		ns
twR	WR Pulse Width		•	60	25		ns
t <sub>LD</sub>	LD Pulse Width		•	110	55		ns
t <sub>CLR</sub>	Clear Pulse Width		•	60	40		ns
t <sub>LWD</sub>	WR to LD Delay Time			0			ns
Power Sup							
I <sub>CC</sub>	Supply Current, V <sub>CC</sub>	Digital Inputs = 0V or V <sub>CC</sub>	•		1.5	10	μA
I <sub>S</sub>	Supply Current, V <sup>+</sup> , V <sup>-</sup>	±15V ±5V	•		4.5 4.0	7.0 6.8	mA mA
V <sub>CC</sub>	Supply Voltage			4.5	5	5.5	V
V+	Supply Voltage			4.5		16.5	V
V-	Supply Voltage			-16.5		-4.5	V



# **ELECTRICAL CHARACTERISTICS**

**Note 1:** Absolute Maximum Ratings are those values beyond which the life of a device may be impaired.

Note 2:  $\pm 1LSB = \pm 0.0015\%$  of full scale =  $\pm 15.3$  ppm of full scale.

Note 3: Using internal feedback resistor.

Note 4: Guaranteed by design, not subject to test.

**Note 5:** I<sub>OUT</sub> with DAC register loaded to all 0s.

Note 6: Typical temperature coefficient is 100ppm/°C.

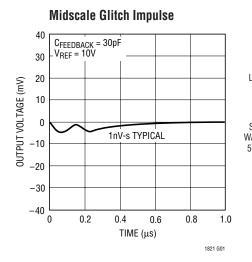
Note 7: Measured in unipolar mode.

Note 8: To 0.0015% for a full-scale change, measured from the rising edge of LD.

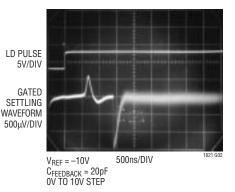
Note 9: REF = 0V. DAC register contents changed from all 0s to all 1s or all 1s to all 0s. LD low and  $\overline{WR}$  high.

Note 11: R1 and R2 are measured between R1 and R<sub>COM</sub>, REF and R<sub>COM</sub>.

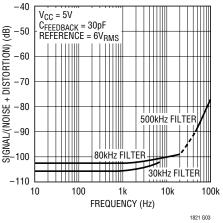
## TYPICAL PERFORMANCE CHARACTERISTICS



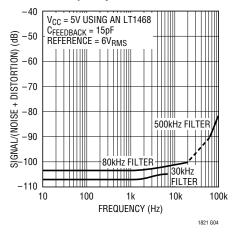
**Full-Scale Setting Waveform** 



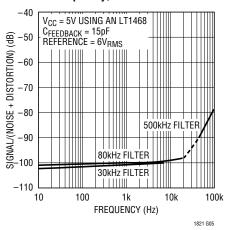
#### Unipolar Multiplying Mode Signal-to-(Noise + Distortion) vs Frequency



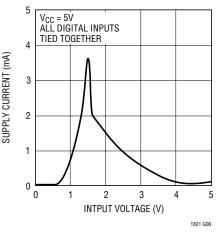
Bipolar Multiplying Mode Signal-to-(Noise + Distortion) vs Frequency, Code = All Zeros



#### Bipolar Multiplying Mode Signal-to-(Noise + Distortion) vs Frequency, Code = All Ones

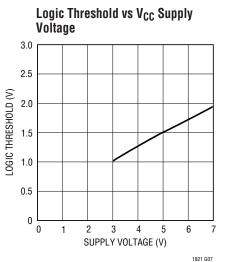


#### V<sub>CC</sub> Supply Current vs Digital Input Voltage

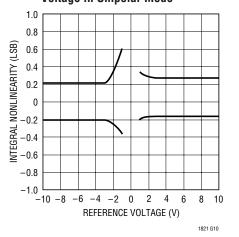




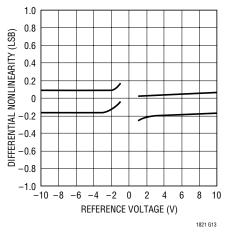
#### TYPICAL PERFORMANCE CHARACTERISTICS

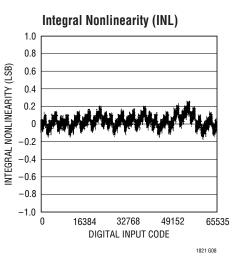


Integral Nonlinearity vs Reference Voltage in Unipolar Mode

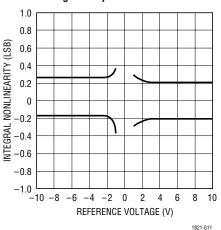


Differential Nonlinearity vs Reference Voltage in Bipolar Mode

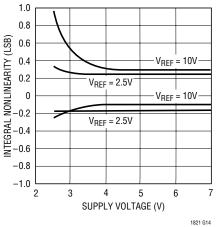


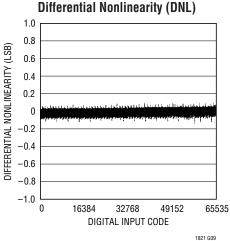


Integral Nonlinearity vs Reference Voltage in Bipolar Mode

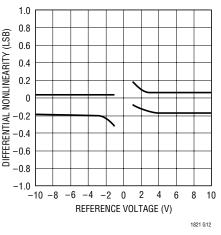


Integral Nonlinearity vs V<sub>CC</sub> Supply Voltage in Unipolar Mode

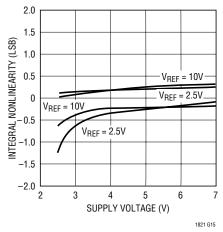




Differential Nonlinearity vs Reference Voltage in Unipolar Mode

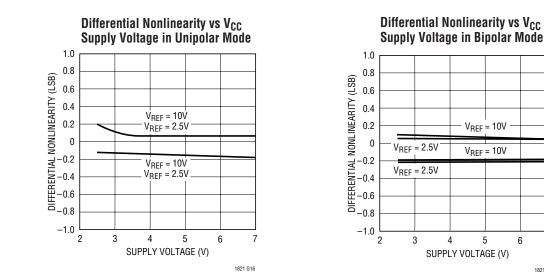


Integral Nonlinearity vs V<sub>CC</sub> Supply Voltage in Bipolar Mode

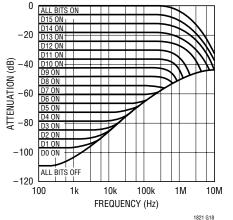




## TYPICAL PERFORMANCE CHARACTERISTICS

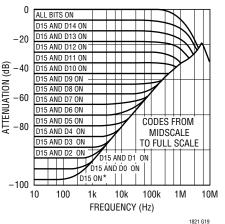


**Unipolar Multiplying Mode Frequency Response vs Digital Code** 

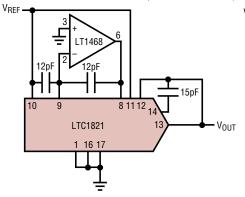


VREF 30pF 9 10 11 12 LTC1821 V<sub>OUT</sub> 16 1

**Bipolar Multiplying Mode Frequency Response vs Digital Code** 



\*DAC ZERO VOLTAGE OUTPUT LIMITED BY BIPOLAR ZERO ERROR TO – 96dB TYPICAL (–78dB MAX, A GRADE)



1821 G17 **Bipolar Multiplying Mode Frequency Response vs Digital Code** 

7

 $V_{REF} = 10V$ 

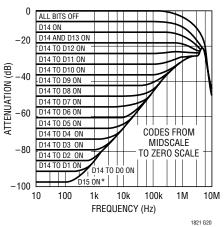
 $V_{REF} = 10V$ 

5

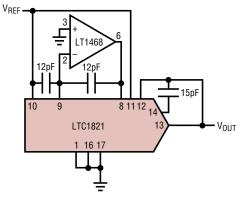
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4

SUPPLY VOLTAGE (V)



\*DAC ZERO VOLTAGE OUTPUT LIMITED BY BIPOLAR ZERO ERROR TO – 96dB TYPICAL (–78dB MAX, A GRADE)





#### PIN FUNCTIONS

DGND (Pin 1): Digital Ground. Connect to analog ground.

 $V_{CC}$  (Pin 2): Positive Supply Input. 4.5V  $\leq V_{CC} \geq 5.5V.$  Requires a bypass capacitor to ground.

D3 (Pin 3): Digital Input Data Bit 3.

D2 (Pin 4): Digital Input Data Bit 2.

D1 (Pin 5): Digital Input Data Bit 1.

**D0 (Pin 6):** LSB or Digital Input Data Bit 0.

**CLR** (Pin 7): Digital Clear Control Function for the DAC. When CLR is taken to a logic low, it sets the DAC output and all internal registers to: zero code for the LTC1821 and midscale code for the LTC1821-1.

**REF (Pin 8):** Reference Input and 4-Quadrant Resistor R2. Typically  $\pm 10V$ , accepts up to  $\pm 15V$ . In 2-quadrant mode, tie this pin to the external reference signal. In 4-quadrant mode, this pin is driven by external inverting reference amplifier.

**R**<sub>COM</sub> (Pin 9): Center Tap Point of the Two 4-Quadrant Resistors R1 and R2. Normally tied to the inverting input of an external amplifier in 4-quadrant operation. Otherwise this pin is shorted to the REF pin. See Figures 1 and 2.

**R1 (Pin 10):** 4-Quadrant Resistor R1. In 2-quadrant operation, short this pin to the REF pin. In 4-quadrant mode, tie this pin to the external reference signal.

 $R_{OFS}$  (Pin 11): Bipolar Offset Resistor. Typically swings ±10V, accepts up to ±15V. For 2-quadrant operation, tie this pin to  $R_{FB}$  and for 4-quadrant operation, tie this pin to R1.

 $\textbf{R_{FB}}$  (Pin12): Feedback Resistor. Normally connected to  $V_{OUT}.$  Typically swings  $\pm 10V.$  The voltage at this pin swings 0 to  $V_{REF}$  in unipolar mode and  $\pm V_{REF}$  in bipolar mode.

 $V_{OUT}$  (Pin 13): DAC Voltage Output. Normally connected to R<sub>FB</sub> and to I<sub>OUT</sub> through a 22pF feedback capacitor in unipolar mode (15pF in bipolar mode). Typically swings ±10V.

 $I_{OUT}$  (Pin 14): DAC Current Output. Normally tied through a 22pF feedback capacitor in unipolar mode (15pF in bipolar mode) to  $V_{OUT}.$ 

**V<sup>+</sup> (Pin 15):** Amplifier Positive Supply. Range is 4.5V to 16.5V.

**AGNDS (Pin 16):** Analog Ground Sense. Connect to analog ground.

**AGNDF (Pin 17):** Analog Ground Force. Connect to analog ground.

**DNC (Pin 18, 19, 21):** Connected internally. Do not connect external circuitry to these pins.

**V<sup>-</sup> (Pin 20):** Amplifier Negative Supply. Range is -4.5V to -16.5V.

NC (Pin 22): No Connection.

**LD (Pin 23):** DAC Digital Input Load Control Input. When LD is taken to a logic high, data is loaded from the input register into the DAC register, updating the DAC output.

 $\overline{WR}$  (Pin 24): DAC Digital Write Control Input. When  $\overline{WR}$  is taken to a logic low, data is written from the digital input pins into the 16-bit wide input reigster.

D15 (Pins 25): MSB or Digital Input Data Bit 15.

D14 (Pin 26): Digital Input Data Bit 14.

D13 (Pin 27): Digital Input Data Bit 13.

D12 (Pin 28): Digital Input Data Bit 12.

D11 (Pin 29): Digital Input Data Bit 11.

D10 (Pin 30): Digital Input Data Bit 10.

D9 (Pin 31): Digital Input Data Bit 9.

D8 (Pin 32): Digital Input Data Bit 8.

- D7 (Pin 33): Digital Input Data Bit 7.
- D6 (Pin 34): Digital Input Data Bit 6.
- D5 (Pin 35): Digital Input Data Bit 5.

D4 (Pin 36): Digital Input Data Bit 4.

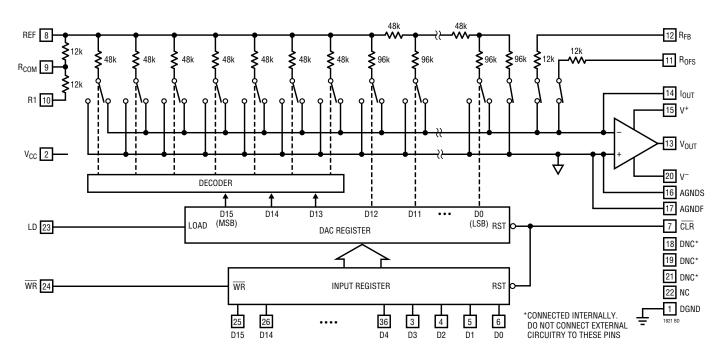


# TRUTH TABLE

#### Table 1

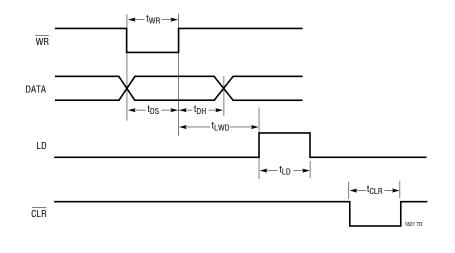
CONTROL INPUTS		PUTS	
CLR	WR	LD	REGISTER OPERATION
0	Х	Х	Reset Input and DAC Register to All 0s for LTC1821 and Midscale for LTC1821-1 (Asynchronous Operation)
1	0	0	Write Input Register with All 16 Data Bits
1	1	1	Load DAC Register with the Contents of the Input Register
1	0	1	Input and DAC Register Are Transparent
1			CLK = LD and WR Tied Together. The 16 Data Bits Are Written Into the Input Register on the Falling Edge of the CLK and Then Loaded Into the DAC Register on the Rising Edge of the CLK
1	1	0	No Register Operation

## **BLOCK DIAGRAM**





#### TIMING DIAGRAM



## **APPLICATIONS INFORMATION**

#### Description

The LTC1821 is a 16-bit voltage output DAC with a full parallel 16-bit digital interface. The device can operate from 5V and  $\pm$ 15 supplies and provides both unipolar 0V to -10V or 0V to 10V and bipolar  $\pm$ 10V output ranges from a 10V or -10V reference input. Additionally, the power supplies for the LTC1821 can go as low as 4.5V and  $\pm$ 4.5V. In this case for a 2.5V or -2.5V reference, the output range is 0V to -2.5V, 0V to 2.5V and  $\pm$ 2.5V. The LTC1821 has three additional precision resistors on chip for bipolar operation. Refer to the block diagram regarding the following description.

The 16-bit DAC consists of a precision R-2R ladder for the 13 LSBs. The three MSBs are decoded into seven segments of resistor value R. Each of these segments and the R-2R ladder carries an equally weighted current of one eighth of full scale. The feedback resistor  $R_{FB}$  and 4-quadrant resistor  $R_{OFS}$  have a value of R/4. 4-quadrant resistors R1 and R2 have a magnitude of R/4. R1 and R2 together with an external op amp (see Figure 2) inverts the reference input voltage and applies it to the 16-bit DAC input REF, in 4-quadrant operation. The REF pin presents a constant input impedance of R/8 in unipolar mode and R/12 in bipolar mode.

The LTC1821 contains an onboard precision high speed amplifier. This amplifier together with the feedback resistor (R<sub>FB</sub>) form a precision current-to-voltage converter for the DAC's current output. The amplifier has very low noise, offset, input bias current and settles in less than 2µs to 0.0015% for a 10V step. It can sink and source 22mA ( $\pm$ 15V) typically and can drive a 300pF capacitive load. An added feature of these devices, especially for waveform generation, is a proprietary deglitcher that reduces glitch impulse to below 2nV-s over the DAC output voltage range.

#### **Digital Section**

The LTC1821 has a 16-bit wide full parallel data bus input. The device is double-buffered with two 16-bit registers. The double-buffered feature permits the update of several DACs simultaneously. The input register is loaded directly from a 16-bit microprocessor bus when the WR pin is brought to a logic low level. The second register (DAC register) is updated with the data from the input register when the LD signal is brought to a logic high. Updating the DAC register updates the DAC output with the new data. To make both registers transparent in flowthrough mode, tie WR low and LD high. However, this defeats the deglitcher operation and output glitch impulse may increase. The deglitcher is activated on the rising edge of the LD pin. The

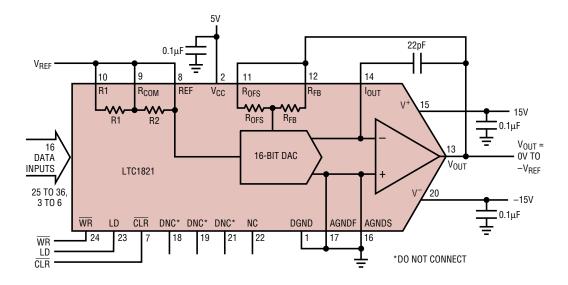


versatility of the interface also allows the use of the input and DAC registers in a master slave or edge-triggered configuration. This mode of operation occurs when WR and LD are tied together. The asynchronous clear pin resets the LTC1821 to zero scale and the LTC1821-1 to midscale. CLR resets both the input and DAC registers. These devices also have a power-on reset. Table 1 shows the truth table for the LTC1821.

#### Unipolar Mode

#### (2-Quadrant Multiplying, $V_{OUT} = 0V \text{ to } - V_{REF}$ )

The LTC1821 can be used to provide 2-quadrant multiplying operation as shown in Figure 1. With a fixed -10Vreference, the circuit shown gives a precision unipolar 0V to 10V output swing.



В	NARY	. INPUT Numbe Egiste	R	ANALOG OUTPUT Vout
MSB			LSB	
1111	1111	1111	1111	-V <sub>BEF</sub> (65,535/65,536)
1000	0000	0000	0000	-V <sub>REF</sub> (32,768/65,536) = -V <sub>REF</sub> /2
0000	0000	0000	0001	-V <sub>BFF</sub> (1/65,536)
0000	0000	0000	0000	OV

1821 F01

Figure 1. Unipolar Operation (2-Quadrant Multiplication)  $V_{OUT} = 0V$  to  $-V_{REF}$ 

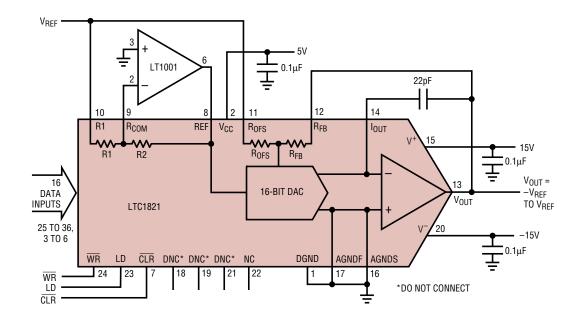


#### **Bipolar Mode**

#### (4-Quadrant Multiplying, $V_{OUT} = -V_{REF}$ to $V_{REF}$ )

The LTC1821 contains on chip all the 4-quadrant resistors necessary for bipolar operation. 4-quadrant multiplying

operation can be achieved with a minimum of external components—a capacitor and a single op amp, as shown in Figure 2. With a fixed 10V reference, the circuit shown gives a precision bipolar -10V to 10V output swing.



#### **Bipolar Offset Binary Code Table**

В	INARY	L INPU Numbe Registi	ANALOG OUTPUT V <sub>out</sub>	
MSB			LSB	
1111	1111	1111	1111	V <sub>REF</sub> (32,767/32,768)
1000	0000	0000	0001	V <sub>REF</sub> (1/32,768)
1000	0000	0000	0000	OV
0111	1111	1111	1111	-V <sub>REF</sub> (1/32,768)
0000	0000	0000	0000	-V <sub>REF</sub>
				1821 F02



Figure 2. Bipolar Operation (4-Quadrant Multiplication)  $V_{OUT} = -V_{REF}$  to  $V_{REF}$ 

#### Precision Voltage Reference Considerations

Because of the extremely high accuracy of the 16-bit LTC1821, careful thought should be given to the selection of a precision voltage reference. As shown in the section describing the basic operation of the LTC1821, the output voltage of the DAC circuit is directly affected by the voltage reference; thus, any voltage reference error will appear as a DAC output voltage error.

There are three primary error sources to consider when selecting a precision voltage reference for 16-bit applications: output voltage initial tolerance, output voltage temperature coefficient (TC), and output voltage noise.

Initial reference output voltage tolerance, if uncorrected, generates a full-scale error term. Choosing a reference with low output voltage initial tolerance, like the LT1236 ( $\pm 0.05\%$ ), minimizes the gain error due to the reference; however, a calibration sequence that corrects for system zero- and full-scale error is always recommended.

A reference's output voltage temperature coefficient affects not only the full-scale error, but can also affect the circuit's INL and DNL performance. If a reference is chosen with a loose output voltage temperature coefficient, then the DAC output voltage along its transfer characteristic will be very dependent on ambient conditions. Minimizing the error due to reference temperature coefficient can be achieved by choosing a precision reference with a low output voltage temperature coefficient and/or tightly controlling the ambient temperature of the circuit to minimize temperature gradients.

As precision DAC applications move to 16-bit and higher performance, reference output voltage noise may contribute a dominant share of the system's noise floor. This in turn can degrade system dynamic range and signal-tonoise ratio. Care should be exercised in selecting a voltage reference with as low an output noise voltage as practical for the system resolution desired. Precision voltage references, like the LT1236, produce low output noise in the 0.1Hz to 10Hz region, well below the 16-bit LSB level in 5V or 10V full-scale systems. However, as the circuit bandwidths increase, filtering the output of the reference may be required to minimize output noise.

#### Grounding

As with any high resolution converter, clean grounding is important. A low impedance analog ground plane and star grounding should be used. AGNDF and AGNDS must be tied to the star ground with as low a resistance as possible. When it is not possible to locate star ground close to AGNDF and AGNDS, separate traces should be used to route these pins to the star ground. This minimizes the voltage drop from these pins to ground due to the code dependent current flowing into the ground plane. If the resistance of these separate circuit board traces exceeds  $1\Omega$ , the circuit of Figure 3 eliminates this code dependent voltage drop error for high resistance traces.

To calculate PC track resistance in squares, divide the length of the PC track by the width and multiply this result by the sheet resistance of copper foil. For 1 oz copper ( $\approx 1.4$  mils thick), the sheet resistance is 0.045 $\Omega$  per square.

REFERENCE	INITIAL Tolerance	TEMPERATURE DRIFT	0.1Hz to 10Hz NOISE
LT1019A-5, LT1019A-10	±0.05%	5ppm/°C	12µV <sub>Р-Р</sub>
LT1236A-5, LT1236A-10	±0.05%	5ppm/°C	3µV <sub>P-P</sub>
LT1460A-5, LT1460A-10	±0.075%	10ppm/°C	20µV <sub>P-P</sub>
LT1790A-2.5	±0.05%	10ppm/°C	12µV <sub>Р-Р</sub>

 Table 2. Partial List of LTC Precision References Recommended

 for Use with the LTC1821, with Relevant Specifications



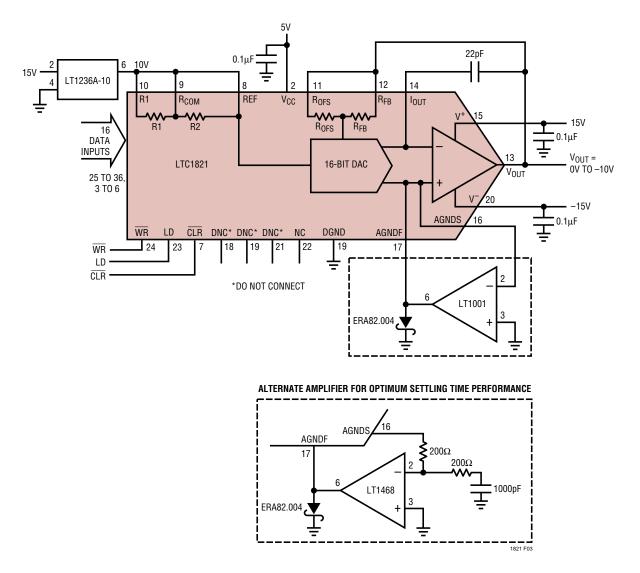
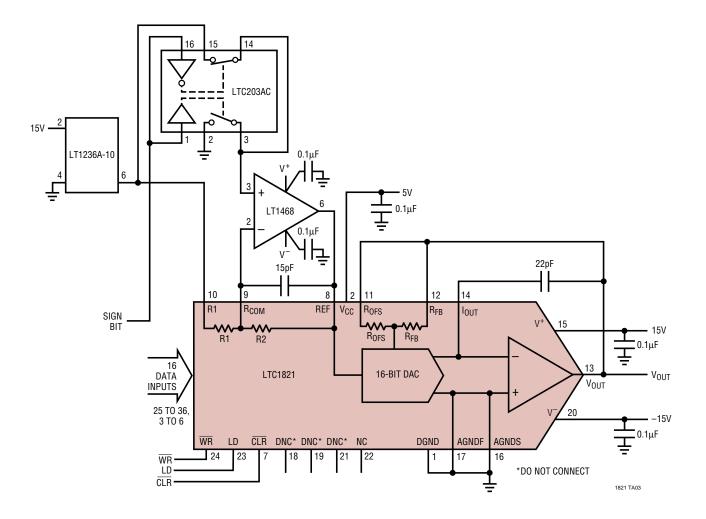


Figure 3. Driving AGNDF and AGNDS with a Force/Sense Amplifier



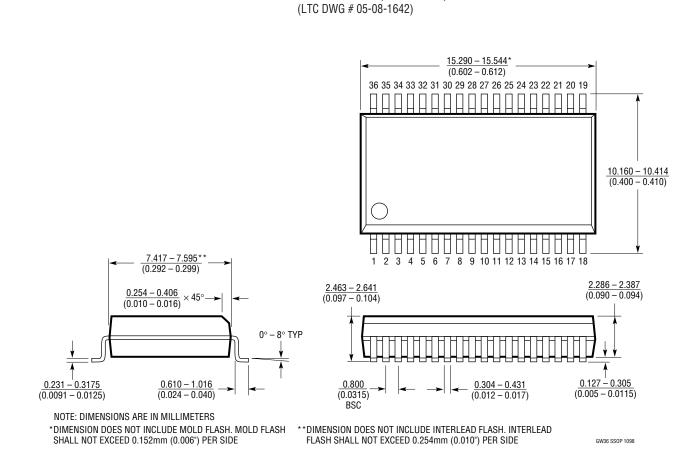
## TYPICAL APPLICATION

17-Bit Sign Magnitude Output Voltage DAC with Bipolar Zero Error of  $140 \mu V$  (0.92LSB at 17 Bits)





#### **PACKAGE DESCRIPTION** Dimensions in inches (millimeters) unless otherwise noted.



GW Package 36-Lead Plastic SSOP (Wide 0.300)



## **RELATED PARTS**

PART NUMBER		DESCRIPTION	COMMENTS		
ADCs	LTC1417	Low Power 400ksps, 14-Bit ADC	20mW, Single or ±5V, Serial I/O		
	LTC1418	14-Bit, 200ksps, Single 5V ADC	15mW, Serial/Parallel ±10V		
	LTC1604/LTC1608	16-Bit, 333ksps/500ksps, ±5V ADC	90dB SINAD, 100dB THD, ±2.5V Inputs		
	LTC1605/LTC1606	16-Bit, 100ksps/250ksps, Single 5V ADC	$\pm 10V$ Inputs, 55mW/75mW, Byte or Parallel I/O		
	LTC1609	16-Bit, 200ksps, Single 5V ADC	±10V Inputs, 65mW, Serial I/O		
	LTC2400	24-Bit, Micropower $\Delta\Sigma$ ADC in SO-8	0.3ppm Noise, 4ppm INL, 10ppm Total Unadjusted Error, 200µA		
	LTC2410	24-Bit, Fully Differential, No Latency $\Delta\Sigma$ ADC	0.16ppm Noise, 2ppm INL, 10ppm Total Unadjusted Error, 200µA		
DACs	LTC1591/LTC1597	Parallel 14-/16-Bit Current Output DACs	On-Chip 4-Quadrant Resistors		
	LTC1595/LTC1596	Serial 16-Bit Current Output DACs in SO-8/S16	Low Glitch, ±1LSB Maximum INL, DNL		
	LTC1599	Parallel 2 Byte 16-Bit Current Output DAC	On-Chip 4-Quadrant Resistors		
	LTC1650	Serial 16-Bit $\pm$ 5V Voltage Output DAC	Low Noise and Low Glitch Rail-to-Rail V <sub>OUT</sub>		
	LTC1654	Dual 14-Bit Rail-to-Rail V <sub>OUT</sub> DAC	Programmable Speed/Power, 3.5µs/750µA, 8µs/450µA		
	LTC1655/LTC1655L	Serial 5V/3V 16-Bit Voltage Output DAC in SO-8	Low Power, Deglitched, Rail-to-Rail V <sub>OUT</sub>		
	LTC1657/LTC1657L	Parallel 5V/3V 16-Bit Voltage Output DAC	Low Power, Deglitched, Rail-to-Rail V <sub>OUT</sub>		
	LTC1658	Serial 14-Bit Voltage Output DAC	Low Power, 8-Lead MSOP Rail-to-Rail V <sub>OUT</sub>		
Op Amps	LT1001	Precision Operational Amplifier	Low Offset, Low Drift		
	LT1468	90MHz, 22V/µs, 16-Bit Accurate Op Amp	Precise, 1µs Settling to 0.0015%		
References	LT1019	Bandgap Reference	±0.05% Initial Tolerance, 5ppm/°C		
	LT1236	Precision Buried Zener Reference	$\pm 0.05\%$ Initial Tolerance, Low Noise $3\mu V_{P-P}$		
	LT1460	Micropower Bandgap Reference	±0.075% Initial Tolerance, 10ppm/°C		
	LT1790	SOT-23 Micropower, Low Dropout Reference	±0.05% Initial Tolerance, 10ppm/°C		



## **Mouser Electronics**

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